

Keeping the Listener Engaged: a Dynamic Model of Bayesian Persuasion

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Bayesian Persuasion

- **Classical question:** How (much) can a sender persuade a rational receiver to take a particular action? (e.g., *seller-buyer*, *media-voters*, *prosecutor-judge*, *entrepreneur-investor*....)
- **An important assumption:** **Commitment**, achieved by *instantaneous* and *unrestricted* experimentation. We relax the commitment power with a model that has:
- **Main features:**
 - **Persuasion takes time and cost:** Information takes real time to generate/convey; costly for the sender to generate and for the receiver to process.
 - **No commitment to future actions:** Sender cannot commit to future experiments/persuasion.
- **Questions:**
 - Is dynamic persuasion possible? What payoffs can be achieved?
 - Behavioral implications: Dynamic choice of information structures

Model

- **Two States:** $\omega \in \{L, R\}$
- **Receiver:**
 - chooses a binary action $a \in \{\ell, r\}$
 - prefers to “match” the state: $u_\ell^L > u_r^L, u_r^R > u_\ell^R$, where u_a^ω is payoff from a in state ω .
 - **Notation:**

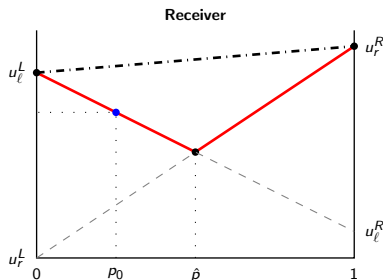
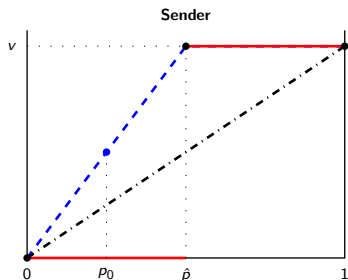
$$U_a(p) = pu_a^R + (1-p)u_a^L, \quad a \in \{\ell, r\}$$

$$U(p) = \max \{U_r(p), U_\ell(p)\} > 0$$

- **Sender:**
 - receives state-independent payoff $v \cdot \mathbf{1}_{\{a=r\}}$
 - performs experiments over time to “persuade” receiver.

Static Benchmark: Kamenica-Gentzkow Model (graphical)

- Sender picks an arbitrary Blackwell experiment.
- Let \hat{p} be such that $U_\ell(\hat{p}) = U_r(\hat{p})$. Suppose prior is $p_0 < \hat{p}$.
- **Solution:** Sender maximizes the prob of inducing posterior $\geq \hat{p}$
 \Rightarrow two beliefs 0 and \hat{p} .



Observations

- R -signal sent excessively compared to full information.
- “Fully-revealing of L ” in case of L -signal
- **The receiver enjoys no rents.**

Our Model: Dynamic Extension

- Continuous time, infinite time horizon.

Timing

At each point $t \geq 0$ in time,

- ① Sender **picks an experiment** (to be described later) at flow cost $c > 0$ or “passes” (= null information)
- ② Receiver **observes the experiment and its outcome**, and either **takes an game-ending action** $a \in \{\ell, r\}$, or **waits**.
 - If the receiver waits and listens to an experiment he incurs flow cost $c > 0$.
 - No cost is incurred if the sender “passes.”

Feasible Experiments: General Poisson Models

- At each point, S chooses a mix of targeted Poisson experiments $i \in I$ with (fractional) units α_i , $\sum_i \alpha_i \leq 1$.
- Each Poisson experiment i generates a signal that arrives with rates $\lambda^L := v^L + \mu$ and $\lambda^R := v^R + \mu$ in states L and R such that $v^L + v^R \leq \lambda$, for some $\lambda > 0$, $\mu \geq 0$.
- Effectively two indistinguishable signals:
 - Real signal: with arrival rates v^L and v^R in states L and R , where $v^L + v^R \leq \lambda$, for some $\lambda > 0$ (“info bound”)
 - Noise (“inflation”): with the same arrival rate μ in each state.
- Sender mixes across $(v_i^L + \mu_i, v_i^R + \mu_i)$ with weights $\alpha_i \Rightarrow$ arrives at rates $\alpha_i(\lambda_L + \mu, \lambda_R + \mu)$.

Illustration of a feasible experiment

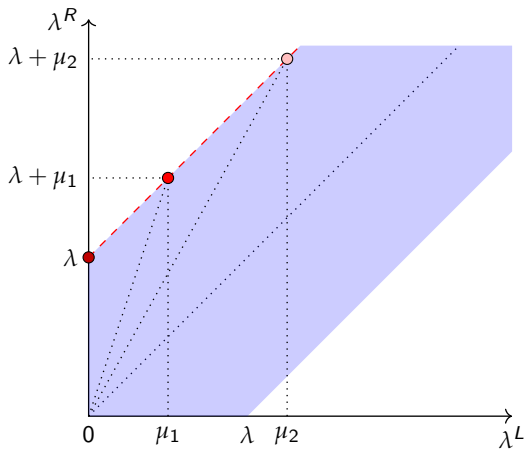


Figure: Arrival rates of feasible Poisson experiments.

Posterior beliefs induced by Poisson jump

- S can choose a feasible (λ^L, λ^R) so that, for any current belief p , a breakthrough signal induces “any” posterior belief q arriving at rate $\frac{p(1-p)}{|q-p|}\lambda$.
- Nests *conclusive good news* or *conclusive bad news*: Set $q = 1$ or 0 .
- Allows for any **directionality** (“good” news $q > p$ or “bad” news $q < p$) and any degree of **accuracy** (q can be far from or close to p), and can mix different Poisson experiments.
- **Important feature**: *Real information takes time; the more precise, the longer it takes.*

Several experiments

L -drifting experiment (with right-jumps $q_+ > p$)

- R -signals: belief jumps to q_+ at arrival rate of $\frac{p(1-p)}{|q_+-p|}\lambda$
- L -signals: belief drifts to the left at rate $\dot{p}_t = -\lambda p(1-p)$

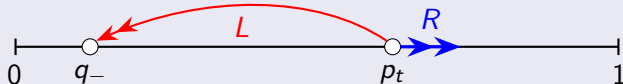


- Sender may choose the “precision” of R -evidence.
 - For example: can target $q_+ = \hat{p}$.
- **Tradeoff**: More precise signals are slower to generate.

Several experiments

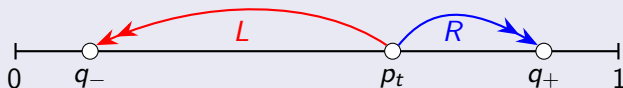
R -drifting experiment (with left-jumps to $q_- < p$):

- L -signals: belief jumps to q_- at rate $\frac{p(1-p)}{|q_- - p|} \lambda$
- R -signals: belief drifts toward right at rate $\dot{p}_t = \lambda p(1-p)$



“Stationary” Experiment

- Splitting attention ($\alpha = 1/2$), we obtain **2 jumps and no drift**
- Jumps to q_- and q_+ at rates $\frac{\lambda p(1-p)}{2|q_\bullet - p|}$, —no drift.



Our Model: Dynamic Extension

Equilibrium

- **Markov Perfect equilibria (MPE):** Subgame perfect equilibrium where strategies depend only on the payoff-relevant state p , regardless of the history.
- **Additional credibility restriction:** The MPE should be a limit of discrete time game equilibria—Sender optimizes even on experiments succeeding with vanishing probability.

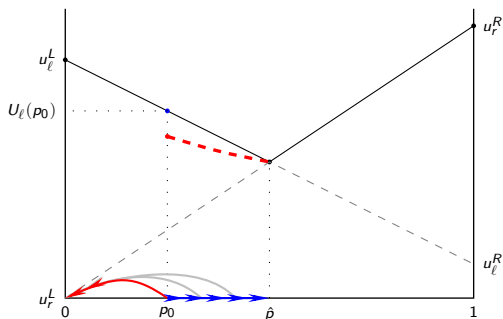
Literature

- **Bayesian Persuasion:** Kamenica and Gentzkow (2011,...), ..., Aumann/Maschler (1995)
- **Wald Decision:** Wald (1947), Arrow, Blackwell, and Girshick (1949), Moscarini and Smith (2001), Che and Mierendorff (2018), Nikandrova and Pancs (2018), Mayskaya (2017), Zhong (2018), **Henry and Ottaviani (2019)**, McClellan (2017)
- **Dynamic Persuasion:** Brocas and Carrillo (2007), Kremer, Mansour and Perry (2014), Au (2015), Ely (2017), Renault, Solan and Vieille (2017), Bizzoto, Rudiger and Vigier (2017), Che and Hörner (2018), **Henry and Ottaviani (2019)**, Ely and Szydlowski (2020), Orlov, Skrzypacz and Zryumov (2020).
- **Repeated Persuasion/Communication:** Margaria and Smolin (2018), Best and Quigley (2017), Mathevet, Pearce, and Stachetti (2018).

Difference: Permanent state, MPE, slow learning.

Dynamic Implementation of Optimal Static Experiment

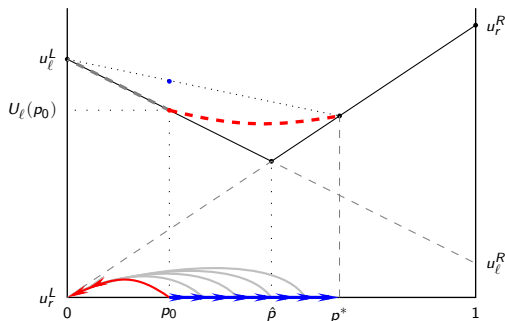
- Fix $p_0 < \hat{p}$.
- Can replicate KG: dynamic experiment that leads to beliefs 0 and \hat{p}
- For example: R -drifting experiment until belief reaches \hat{p} .



- **Problem:** Receiver does not wait if she does not get rent that compensates for flow cost.
⇒ **KG experiment can't persuade receiver to listen.**

Fix: Dynamic Commitment

- *Solves the problem if Sender can commit to future experiments*
 - Example: Commit to R -drifting until the belief reaches $p^* > \hat{p}$.



- Similar to KG except for provision of “rents” to compensate for Receiver’s flow cost. Can approximate KG if $c \rightarrow 0$.
- *But will this work without commitment?*

Is persuasion possible without commitment?

- **No**
 - There is an MPE with total persuasion failure regardless of $c > 0$.
- **Yes**
 - For each $p_0 < \hat{p}$, some dynamic commitment can be supported as MPE if c is low enough.
 - As $c \rightarrow 0$, a **KG experiment** as well as **full revelation** (and anything in between) is dynamically credible. \Rightarrow **Folk Theorem**

MPE: Persuasion Failure

Theorem (Persuasion Failure MPE)

For any $c > 0$, there exists a MPE in which no persuasion occurs.

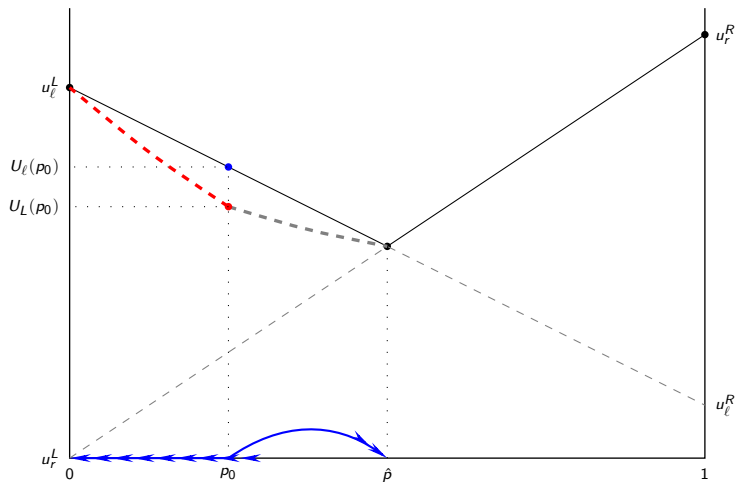
Proof.

MPE strategy profile:

- Receiver never waits—he picks r if $p \geq \hat{p}$ and ℓ for $p < \hat{p}$.
- Sender “passes” if $p \geq \hat{p}$ (or if $p < \hat{p}$ is very low), and performs an L -drifting with jump to \hat{p} if $p < \hat{p}$.



Persuasion failure: illustration



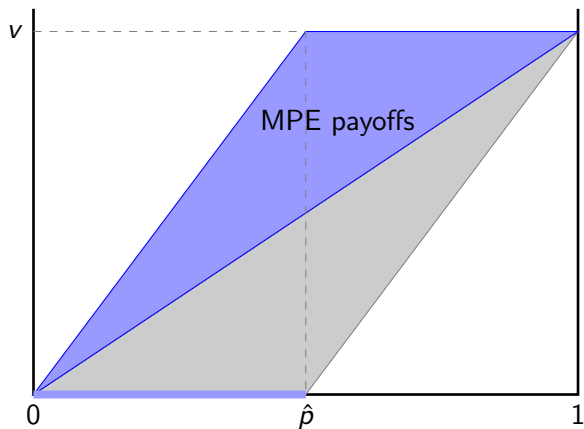
Persuasion MPE: Folk Theorem

More surprisingly, persuasion is possible in MPE. In fact, we can establish a folk theorem.

Theorem (Folk theorem)

Any sender payoff between KG benchmark and "full revelation" is supported in an MPE for any c sufficiently small.

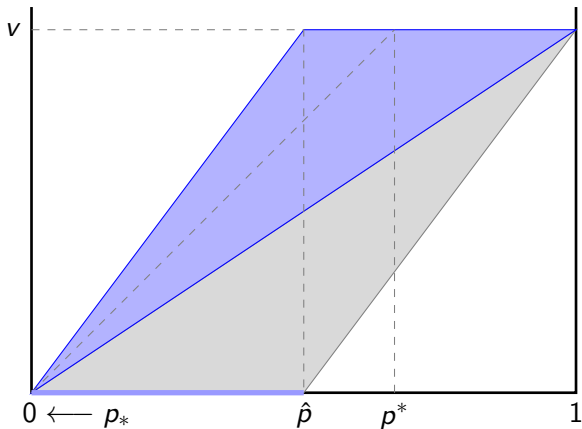
Persuasion MPE: Folk Theorem — Sender's Payoff Set



as $c \rightarrow 0$.

Constructing persuasion equilibria

We construct an MPE in which: S persuades and R waits if $p \in [p_*, p^*]$.



- Dashed line: Equilibrium payoffs for fixed p^* as $c \rightarrow 0$
- Can choose $p^* \searrow \hat{p}$ as $c \rightarrow 0$

Illustration of Persuasion Equilibria

- The construction of persuasion equilibria depend on whether

$$(C1) \quad p^* < \eta, \text{ where } \eta = .943$$

— *how demanding persuasion target p^* is.*

$$(C2) \quad v > U_r(p^*) - U_\ell(p^*).$$

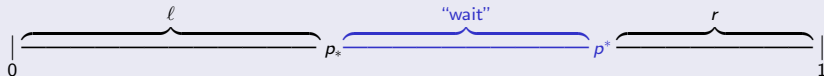
— *relative incentive for S to persuade vs for R to listen.*

MPE under (C1) and (C2)

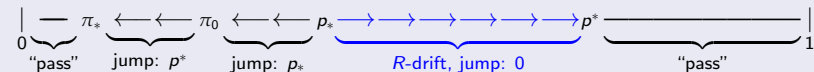
- Given (C1) and (C2), for $c > 0$ sufficiently small, there exists a persuasion MPE with persuasion target p^* :

Persuasion MPE

Receiver's strategy:



Sender's strategy:

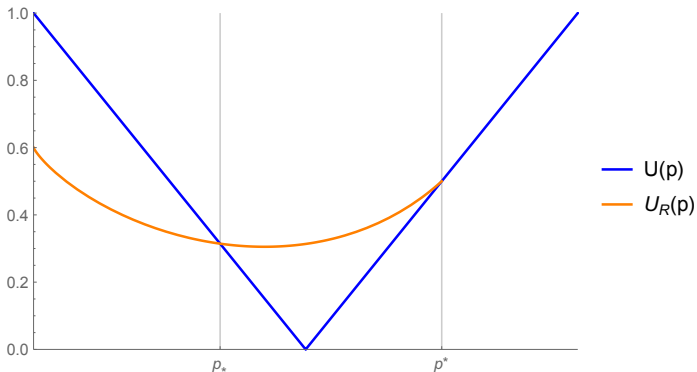
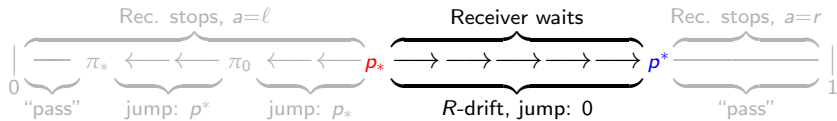


- At p_* , R is indifferent to ℓ and "wait."
- May approximate KG: Can choose $p^* \rightarrow \hat{p}$ and $p_* \rightarrow 0$ as $c \rightarrow 0$.

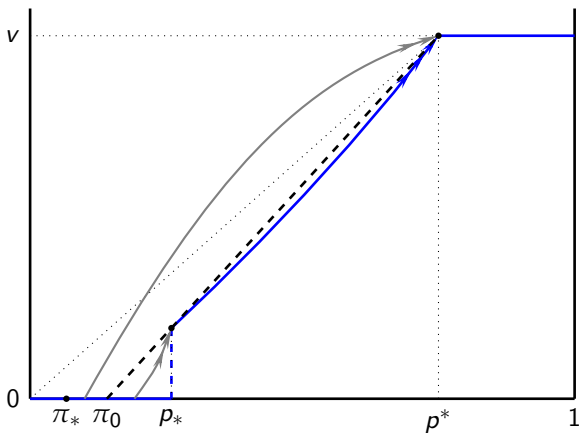
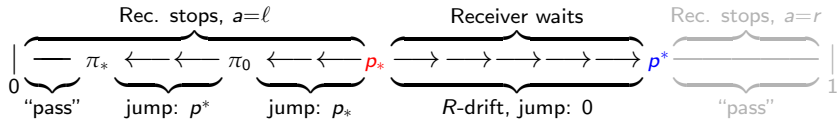
Intuition: *Power of Beliefs*

- Why is Sender continuing to experiment even after reaching \hat{p} ?
Why not stop at \hat{p}
- Suppose Sender stopped at \hat{p} (i.e., “deviated”). \Rightarrow Receiver would never choose r but rather wait.
- Why? Why is Receiver waiting even after \hat{p} is reached?
 \Rightarrow Because, if Receiver waits, Sender will continue experimenting.
- Power of equilibrium beliefs: reminiscent of Che and Skovics, ECMA, 2004.

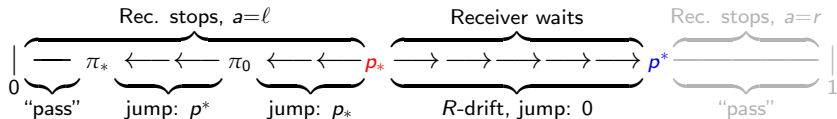
Receiver Incentive



Sender Incentive



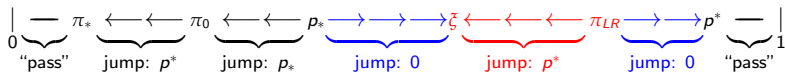
Dynamics of Persuasion



- When Receiver is already interested in listening (i.e., $p \in (p_*, p^*)$):
 - ⇒ Confidence building; tries to rule out L
 - ⇒ Persuasion backloaded.
- When Receiver is skeptical (i.e., $p < p_*$):
 - ⇒ Sender throws a "Hail Mary"
 - ⇒ Persuasion almost surely fails.

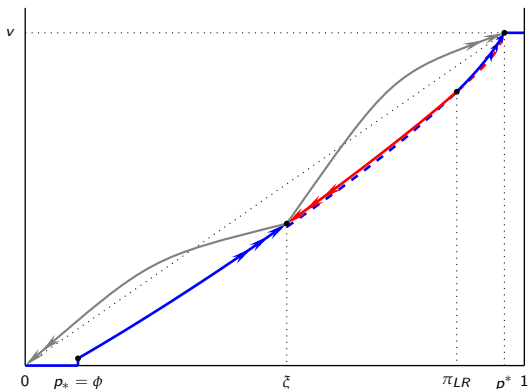
The case of: $p^* > \eta$

- still assume (C2) : $v > U_r(p^*) - U_\ell(p^*)$
- For $c > 0$ small, an MPE looks like:



- At $\tilde{\xi}$: stationary with jumps to $q_- = 0$ and $q_+ = p^*$.
- Alternative dynamic strategies lead to **the same posterior distr** supported on $\{0, p^*\}$.
- *But they differ in expected persuasion costs.*

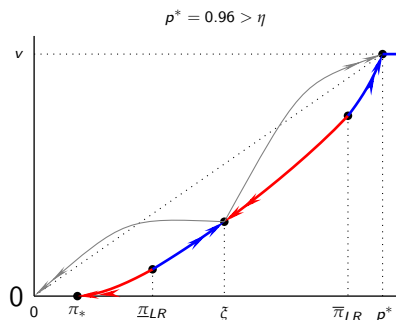
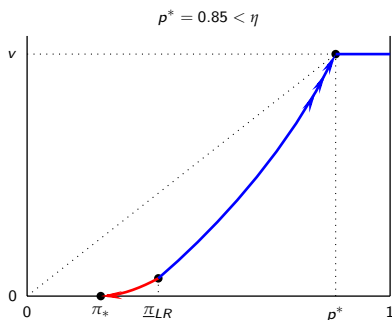
Approximating Full Revelation



- $p_* \rightarrow 0$ as $c \rightarrow 0$
- $\pi_{LR} \rightarrow 1$ and $\zeta \rightarrow 1/2$ as $p^* \rightarrow 1$.

The case of $\neg(C2) : v < U_r(p^*) - U_\ell(p^*)$

Sender's strategies and values:



- For a low $p > p_*$, the sender uses L -drifting—“confidence spending.” Similar to “Hail Mary,” but on path here.
- Posteriors supported on $\{0, \pi_*, p^*\}$.

Summary: Main Contributions

- 1 Introduce sequential information production into Bayesian Persuasion model:
 - Relax commitment power.
 - Power of beliefs allows to sustain persuasion.
- 2 Folk Theorem yields large set of equilibrium outcomes:
 - No persuasion, and any outcome between KG and full revelation can arise.
- 3 Characterize Persuasion Dynamics.
 - Building confidence vs. spending confidence.
 - Persuasion dynamics depend on type of equilibrium.
- 4 Tractable model of dynamic strategic information choice.

Thank you!